

# **Practical Approach to Computer Simulation and Optimization of Complex Thin Profile Extrusion**

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## **ABSTRACT**

The paper presents the development and practical implementation of the FE model for simulation of thin aluminium profile extrusion that is included in the special-purpose program QForm-Extrusion. Due to non-uniform material flow the profile that leaves the orifice may bend, twist or buckle. Other aspects of the material flow such as location of the seam welds in hollow profile extrusion and the propagation of the charge weld in billet-to-billet extrusion are also accurately predicted. The program has a special interface for quick die geometry import and automatic generation of the finite element model. The program automatically recognises bearing zones and converts them into parametric form allowing modification of bearing. Alterations and optimization can be done by using the special module "Bearing Editor" with which the user can achieve the most uniform distribution of longitudinal velocity. The simulation also provides comprehensive analysis of the die stress and deflection. Reasonable simulation time is provided by parallel computations. The software is currently in use at many die making and extrusion companies showing its high economic efficiency.

## **INTRODUCTION**

QForm-Extrusion is a special-purpose program for aluminium profile extrusion simulation that has been developed by QuantorForm Ltd and it is based on our universal metal forming simulation program that has been developing over 20 years. This specialised software includes Lagrange-Euler model for extrusion simulation at the steady state stage [1, 2]. The model is also based the assumption that the tool set is completely filled with the material prior to the beginning of the simulation thus the domain of the material flow inside of the tooling set does not change. This means that the mesh here is immovable while the material flows through it. This approach allows the program not to remesh the domain inside the tools but just to calculate the velocity of the nodes within it. On the other hand the free end of the profile increases in length very quickly after passing through the orifice. Due to non-uniform material flow the profile that leaves the orifice may bend, twist or buckle. The simulation is capable of predicting this undesirable shape deterioration and finding ways to minimize it. It is also very important that with such an approach it is possible to simulate the temperature evolution in the profile after it leaves the die and compare it with the actual temperature measurements that are available at certain distance from the die to tune some parameters of the process. Validation of the model has been performed for prediction of load, material flow pattern, profile temperature and die deformation using special model experiments and numerous industrial case studies done by the program users world-wide. Comprehensive analysis of the program accuracy has been done within the International Extrusion Benchmark Tests by means of comparison of the simulation results with precisely arranged experimental tests. Here the program has shown very good performance (see the tests in Bologna in 2007 [3], Dortmund in 2009 [4] and recently in Bologna in 2011 [5]).

## **BRIEF DESCRIPTION OF THE NUMERICAL MODEL OF EXTRUSION**

From a practical point of view the most important stage of the extrusion process is the quasi steady-state stage when the product shape and its properties are formed. During this quasi steady-state stage some parameters such as the temperature and load do vary due to reducing of the billet length in the container and the heat exchange between extruded material and the tools but this variation can be taken into account by the model still having the same Euler mesh in the extrusion die area. Generally the source data for extrusion simulation include:

- The geometric models of the die set originally created in some Computer-Aided Design (CAD) system.
- The properties of the extruded material (the flow stress data and thermal properties).
- The conditions on the contact surface of the extruded material with the tools (friction, heat transfer coefficient, and temperature of the tools).
- The process parameters (initial temperature of the billet and its distribution, extrusion speed and pulling force).

The simulation of the extrusion process in our program is performed within a so-called simulation domain. The simulation domain is the volume of the extruded material that partially fills the container and completely fills the inner space of the die assembly up to the exit from the bearing. The die set for solid profile extrusions generally includes the feeder or mandrel, the die, the backer and the bolster. Sometimes there may be no feeder at all or the feeder and the die can be made as a single tool. In the case of a hollow profile extrusion, the tooling set includes the mandrel, the die cap, the backer and the bolster. Semi hollow tooling design can be done according to open die or closed die scheme depending on the profile specifics.

In both cases the tooling set is eventually assembled with the container. Thus the extruded material fills the space inside the container and has the contact only with the feeder and the die (solid profile) and with the die cap and the mandrel (hollow profile). The other parts of the die assembly (the backer and the bolster and some other parts) have no direct contact with the material and are not used to create the simulation domain. Their design and properties are only taken into account when simulating the die stress and its deflection.

As a typical example of the model preparation let us consider the experimental die set used for scientific benchmark test presented in Bologna in October 2011. The details of the process and the die design can be found in [5]. The process includes parallel simulation of two similar hollow profiles having big variation of the wall thickness while the die has different design of welding chambers as well as either full or partial support of the die tongue for each of the profile. The profile drawing and stages of the model creation are shown in Fig. 1

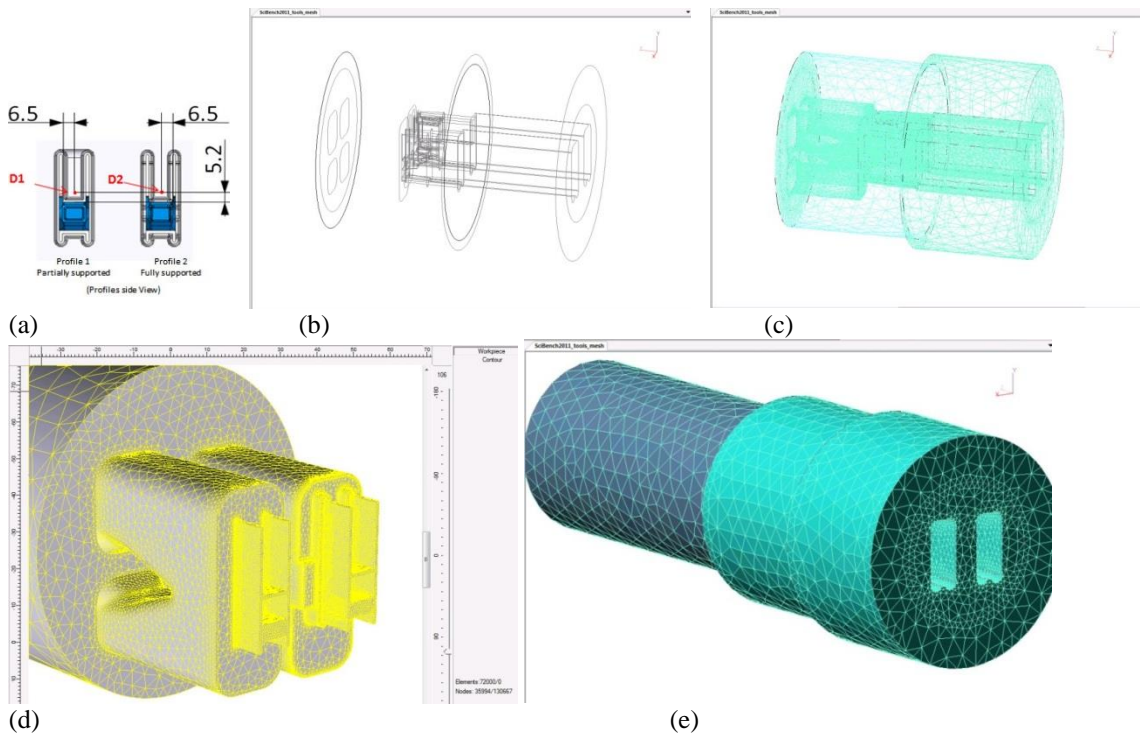


Fig. 1. The scheme of the hollow profiles proposed for scientific benchmark test (a) and subsequent stages of the model preparation: the tool set imported from CAD system (b); the mesh in the tool set (c); the simulation domain with the mesh (d), the whole assembly with the mesh ready for simulation (e).

The mesh inside the domain is built using tetrahedral elements. The quality of the finite element mesh is critical to obtain accurate results. Mesh of insufficient density or with too big a gradient of the element size may cause non-convergence problem and deteriorate the quality of the simulation. It is especially critical if the mesh has improper density distribution at the entrance to the bearing area where the most intensive deformation takes place. In our approach such mesh optimisation is performed automatically without user intervention and it provides necessary background for accurate simulation of the process.

For accurate prediction of the material flow in extrusion process it is also necessary to take into account realistic friction and heat transfer conditions between extruded material and the tooling set. Numerous experimental and theoretical studies show that friction traction on the interface between the tool and deformed material can be represented as a combination of adhesive friction force and the force that is required to deform surface asperities. Thus the expression for friction traction in general can be written as follows:

$$T = T_a + T_d. \quad (1)$$

Where

- $T$  is the total friction traction,
- $T_a$  is the force required to break the adhesive links
- $T_d$  is the force required to deform the asperities.

The adhesive friction component is caused by molecular links of different nature between the body surfaces and is dependent on the material's physical properties. The deformation component is required to deform the asperities and depends on the roughness of the surfaces, flow stress of the deformed material, contact normal pressure and sliding velocity. At high contact pressure the deformation component  $T_d$  is predominant while when the normal pressure is small the adhesive component is relatively more influential.

Depending on the value of the normal contact stress it is necessary to apply different mechanisms of friction as it is explained in our work [6]. Particularly in aluminium extrusions we can clearly distinguish two different areas with respect to friction conditions. The first area covers the inner surface of the container, feeding channels and pockets. Here the contact pressure is very high and the deformation friction factor is close to 1. Due to additional effect of the adhesive friction the total friction traction formally can be bigger than shearing flow stress. This means that the metal sticks to the surface of the tooling set and sliding takes place inside the deformed material by intensive shearing deformation.

The second contact area is the bearing area that can be visible in a special module Bearing Editor during the data preparation when it is represented in parametric form (Fig. 2). In this area we in turn distinguish three zones with different friction models:

1. The sticking zone with predominantly deformation friction. It is situated at the entrance to the bearing and may extend when the bearing has a choke angle.
2. The sliding zone where deformation friction decreases.
3. The zone where the material may separate from the die due to small normal contact stress.

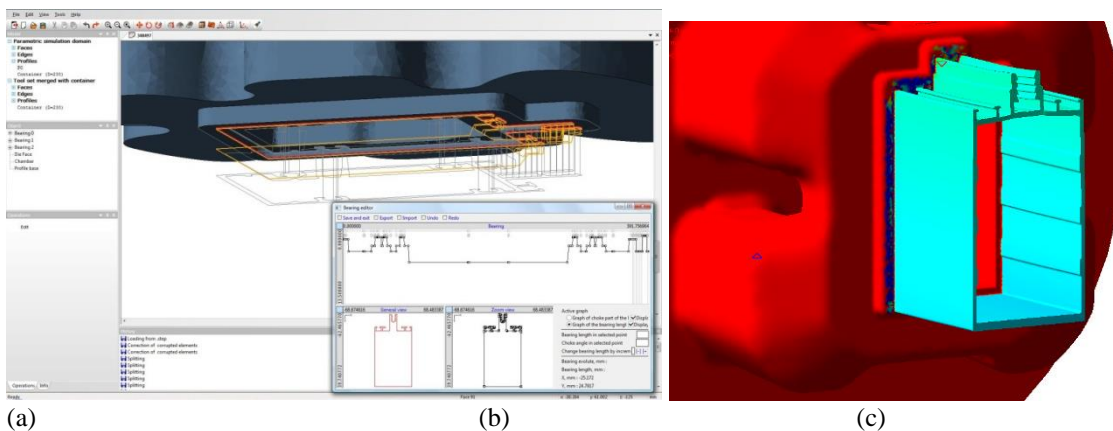


Fig. 2. The contact area subject to transient friction conditions as it is seen in the Bearing Editor (a), the draft of the bearing line (b) and profile extruded after applying the boundary conditions (c).

Relative dimensions of these zones depend on several parameters and may vary along the profile perimeter. The division of the bearing into zones and some of the relations between them have been

experimentally proved by S. Abtahi [7]. Thus for every point along the profile perimeter the following parameters may influence the extent of the zones:

- Actual (effective) choke angle
- Actual thickness of the profile
- Velocity of the profile flow.

The effective choke angle is the algebraic sum of the choke angle as it was originally manufactured in the die and the angle of the bearing surface inclination that appears due to tool deformation. The profile thickness also may vary due to the die deformation. Thus to get the precise results of the material flow we need to take into account the variation of the effective choke angle and the actual thickness of the profile. To get these values the material flow problem is to be coupled with the simulation of the tool deformation. Now the friction model developed for the simulation includes the influence of the elastic deformation of the tooling set on the effective angle and the profile thickness [6].

Such a complicated friction model cannot be expressed analytically thus it is realized as an iterative semi empiric algorithm. Firstly we simulate the material flow and solve the die deformation problem. Then we calculate effective choke angle and actual profile thickness at every point of the bearing perimeter and solve the material flow problem again. For every zone in every point of the bearing perimeter we calculate the friction stress depending on velocity, normal contact stress and flow stress.

## MATERIAL FLOW AND THE MODEL VERIFICATION

The numerical model described above has been tested using both dedicated laboratory tests and cases from routine industrial practice. One of the most recent laboratory tests has been done within the conference ICEB 2011 and its results have been reported by us in [8]. The data summary and experimental results presented by the organisers can be found in [5]. The profile sketch and the tooling set are shown in Fig. 1 while here we would like to discuss some results on the material flow prediction.

As seen from the simulation results the profile 1 tends to go much faster than the profile 2 (Fig.3 a and b). In the same time the simulation shows that due to different design of the welding chambers and other parts of the dies the profile 1 (on the left) has the trend to be bent downwards while the profile 2 is going more or less straight. The experimental data when have been disclosed at the conference have shown exactly the same trend in real material flow. The front pieces of the profiles are shown on the photos (Fig. 3, c and d) and are in good agreement with predictions. The same good correspondence with experiment has been observed in predicting the relative velocity of the profiles 1 and 2, the extrusion load, the profile temperature and the die deformation that can be found in [5] and [8].

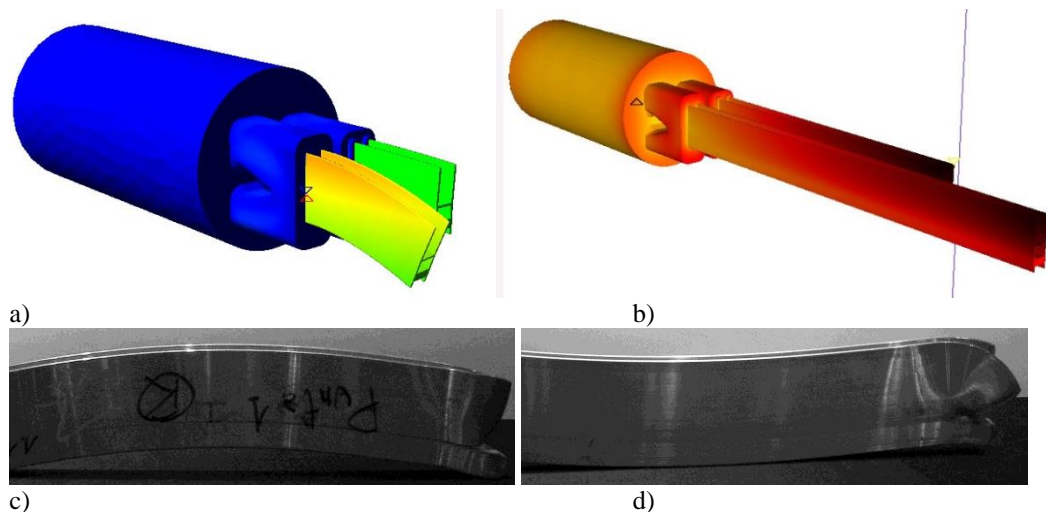


Fig. 3. The simulation of the profiles flow in the test: (a) – free flow of the profiles with the velocity distribution, bending is shown; (b) – the same profiles simulation when the guides are applied to prevent profiles bending; (c) - photo of the profile 1 that bends downwards; (d) - photo of the profile 2 going mostly straight.

Industrial verification of the model was done using a wide range of solid and hollow profiles of various complexity and extrusion ratios that are produced by different companies world-wide. Here there is one

case study from Ekstek-Nord Ltd. (Belaya Kalitva, Russia) where more than 15 profiles were carefully investigated. It is impossible to measure the velocity distribution along the profile contour in a real extrusion. Thus the only way is to compare the shape of the front tip of a real profile with the shape of its front end predicted in simulation. The shape of the front tip in both cases clearly shows inequality of the velocity in different parts of the profile. There were several goals of such industrial investigation:

- Testing and improving the methods of the geometry data transfer from industrial systems of die design into the simulation program.
- Estimation of the accuracy of the simulation.
- Use the results of the tests for further development of the numerical model and the software.

The results obtained in these tests have shown very good correspondence between the simulation and real extrusion as can be seen by comparing the shapes of the front tips for the profiles. For example, the central web of the profile in Fig. 4 is the slowest segment of the product and its velocity is nearly zero so it didn't go through the die. The same defect is clearly observed in the experiment (Fig. c and d). To fix the defect and to correct this initial die design it is necessary to increase the cross-sectional area of the central feeding channel and to modify the length of the bearing along the profile. This was done in practice and the extrusion was produced correctly.

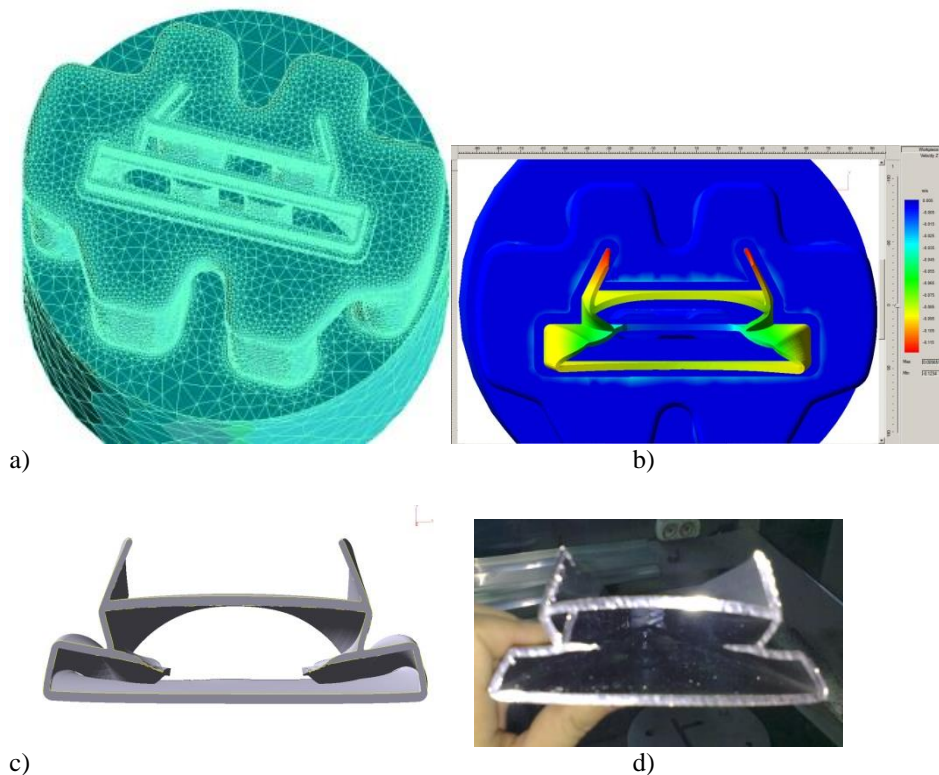


Fig. 4. The simulation of the industrial hollow profile: (a) – the simulation domain with the mesh; (b) – the front tip of the profile with the velocity distribution; (c) – the crosscut of the simulated profile that shows that central web didn't come through the die; (d) – the same crosscut of the real profile with absent central web.

## PREDICTION OF SEAM WELDS AND CHARGE WELDS IN EXTRUSION

Besides of the profile shape accuracy there are some other aspects of the product quality also related to the material flow pattern. Actually there are three types of defects that have to be avoided in extrusion practice: contamination of billet skin and its penetration in the product known as back-end-defect, improper location of seam welds (longitudinal welds) in hollow profiles and too much extended charge welds transition (transversal welds) between an old and a new billet in billet-to-billet extrusion. All these phenomena can be successfully predicted and corrected or at least minimized by means of simulation as it is illustrated by the examples proved by laboratory and industrial tests below.

The program has facilities to trace the material flow from the container through feeding channels to the finish profile and by these means it effectively finds out the locations of the material paths from the billet skin into the product as well as the locations of the weld seams of both types. Firstly, let us illustrate this ability using the same scientific benchmark test from Bologna 2011 as was mentioned above. The authors of the test have provided the results about location of longitudinal seam welds for both profiles. After the extrusion the profiles have been cut and etched. Their cross sections in magnified scale are shown on Fig. 5 c and d. It is clearly seen that the welds of profile 2 are located just below the bridge axes while the welds of profile 1 are near the bottom part of the profile that is the result of material speed difference in the feeders.

In the simulation the program traces the material flow through the feeding channels that are highlighted by different colors (see Fig. 5 b) and then it shows over the areas where these material streams do merge in the profile crosscuts (Fig. 5 a). The simulation predicts exactly the same locations of the seam welds as they are seen in reality (Fig. 5 c and d). In profile 2 they are closer to the bridge axis while in profile 1 they are significantly shifted downwards to the corners.

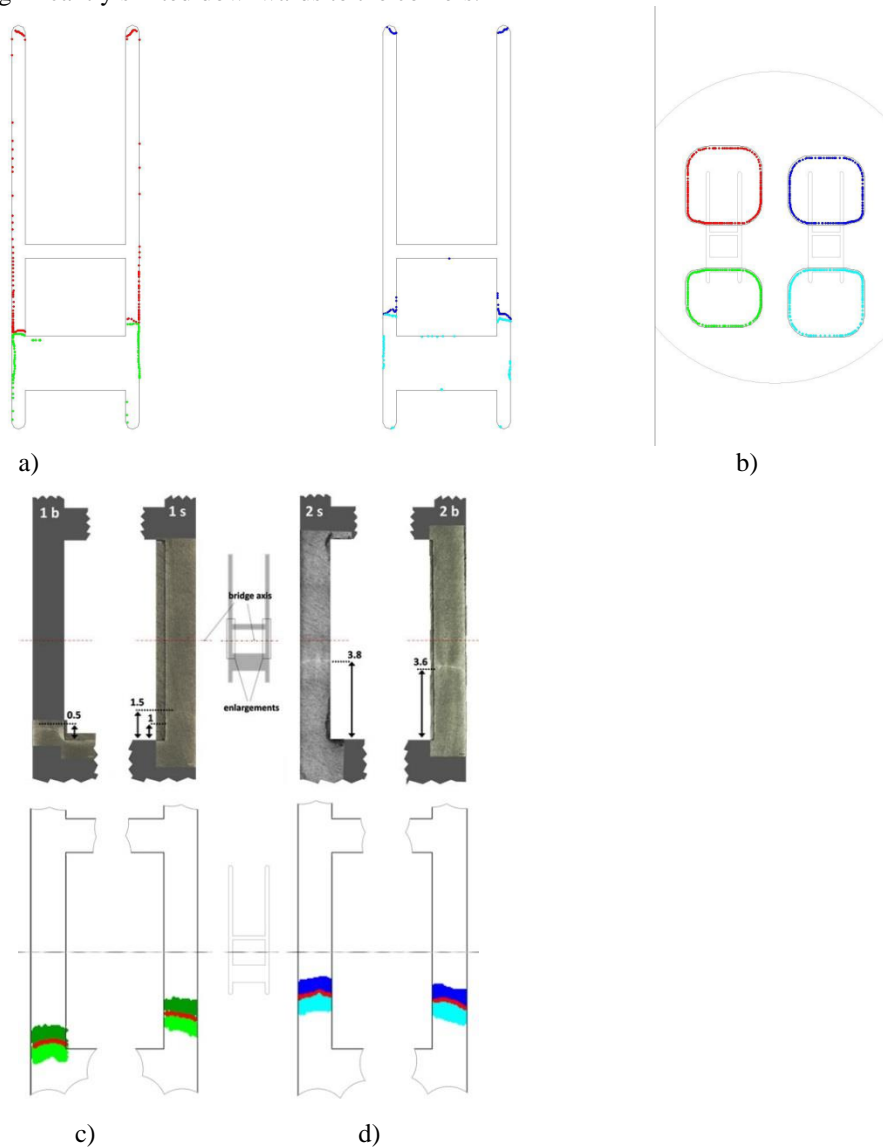
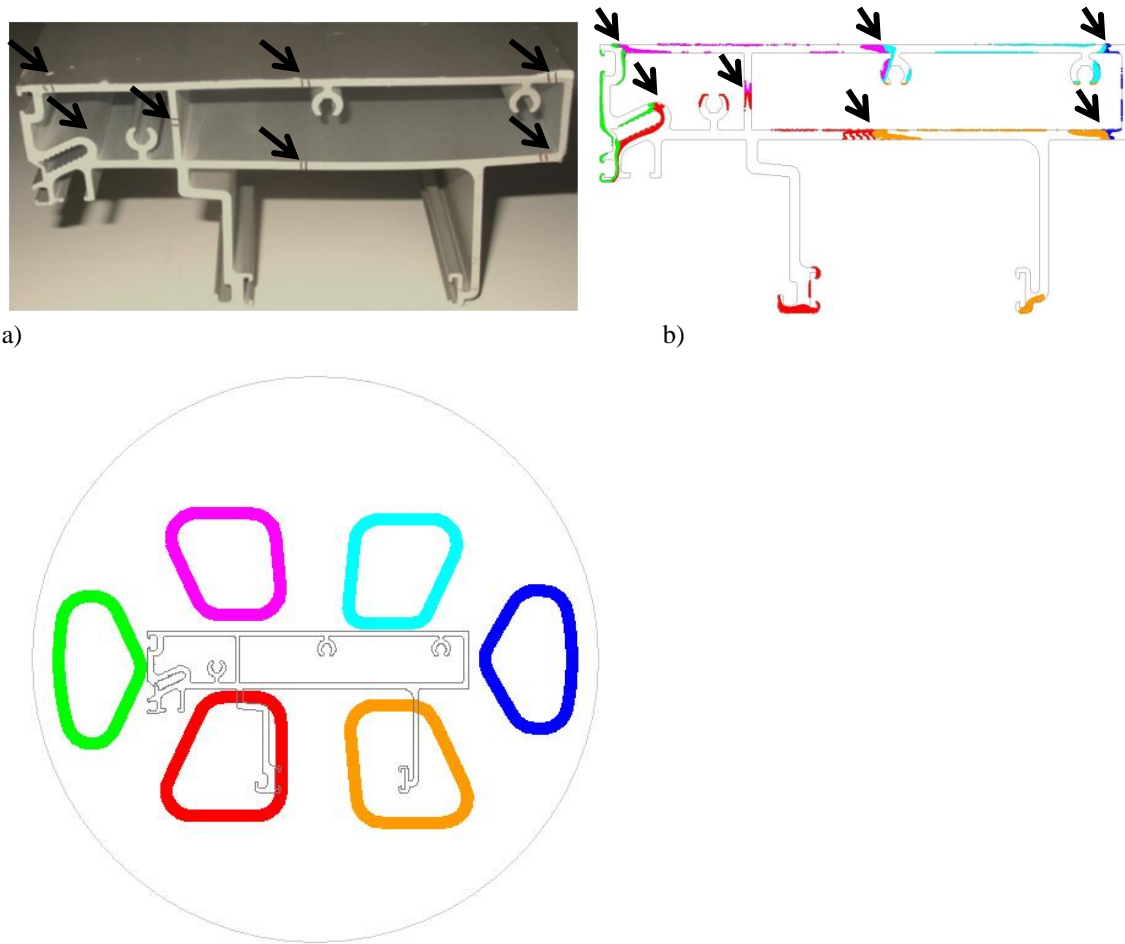


Fig. 5. The location of the seam welds obtained in simulation (a) and contours of feeding channels overlapped over the profile contours (b). Comparison of the seam weld locations in magnified scale for profile 1 (c) and profile 2 (d) obtained experimentally (photos above) and by means of simulation (below).

The seam weld position is very important for industrial profiles. Meanwhile due to their shape complexity it is very difficult to predict a priori where the welds may appear. Non proper position of the welding lines

may even cause crash of constructions where such profiles are used. To check the accuracy of the seam weld prediction for more complicated industrial profiles several examples have been used and checked. One of them is presented in the Fig. 5<sup>1</sup>. As clearly seen from this comparison the prediction is accurate enough to be used for routine check of the profiles at the stage of the tooling design to avoid possible problems due to inappropriate seam weld location.

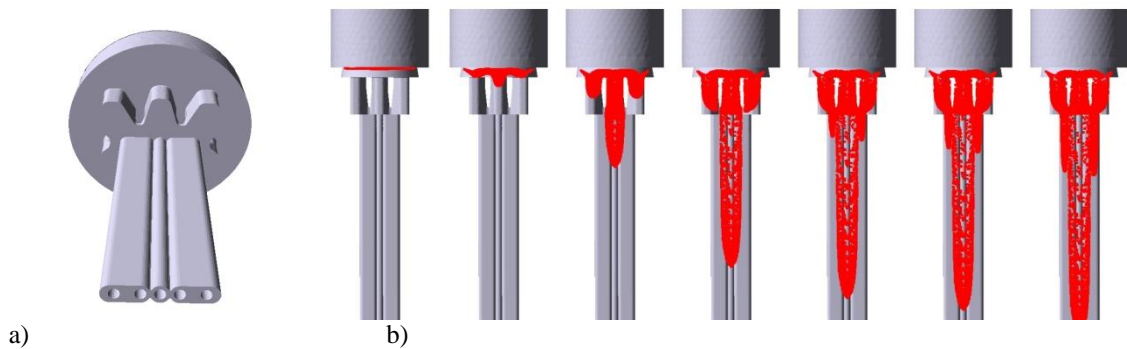


c)  
 Fig. 5. Experimental (a), predicted (b) locations of the seam welds (shown by arrows) and location of feeding channels in the tooling set shown over the profile contour (c)

Charge or transverse welds are generated between the old and the new billet during continuous extrusion. On the contrary to seam welds the charge welds usually contain contamination of oxides or other substances that are responsible for lower mechanical properties along them. Thus charge welds are to be discarded from the finish profile. In industrial practice quite often it is not easy to find their positions and costly microstructure investigations are to be done.

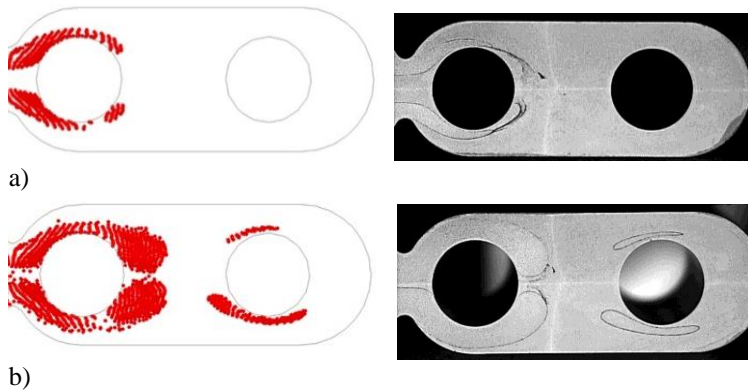
The accuracy of the model prediction capabilities for transverse welds has been tested using an industrial example proposed by SAPA Technology (Sweden). To show the propagation of the transversal seam weld inside the extruded profile the charge plane is to be specified. This plane initially separates new and old material. The pictures in Fig. 6 show propagation of the material from a “new” billet through “old” one.

<sup>1)</sup> With kind permission of COMPES, Italy



a)  
b)  
Fig. 6. General view of the extruded profile (a) and the progress of propagation of the new billet material (red) into the product (b).

More comprehensive view of the charge weld and its comparison with experimental data is shown on Fig. 7. The crosscuts show how “new” material expands through the profile during the progress of the extrusion. The comparison has shown the high accuracy of the numerical prediction.



a)  
b)  
Fig. 7. New material shown by red colour in the extruded profile predicted in simulation (left) and the photos of etched crosscuts (right) for the same different positions (a and b)<sup>2</sup>.

## CONCLUSIONS

1. The developed extrusion simulation model is based on Lagrange-Euler approach with specially optimized finite element mesh in the simulation domain.
2. Aluminium extrusion model requires consideration of more complicated friction law that includes the influence of adhesion friction.
3. The program has validated by model and industrial experiments showing good accuracy of the results in terms of material flow prediction, the actual profile shape and other vital process parameters.
4. Accurate prediction of the material flow allows analyzing of longitudinal and transversal seam welds that often are critical for the product quality and are to be optimized at the stage of the tool design.
5. The program is an ideal tool for wide range of industrial and research implementations in the field of thin profile extrusion.

<sup>2)</sup> With kind permission of SAPA Technology, Sweden



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